

Diagonal and unipotent flows

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Basic setting

Let G be a Lie group.

Let Γ be a lattice in G .

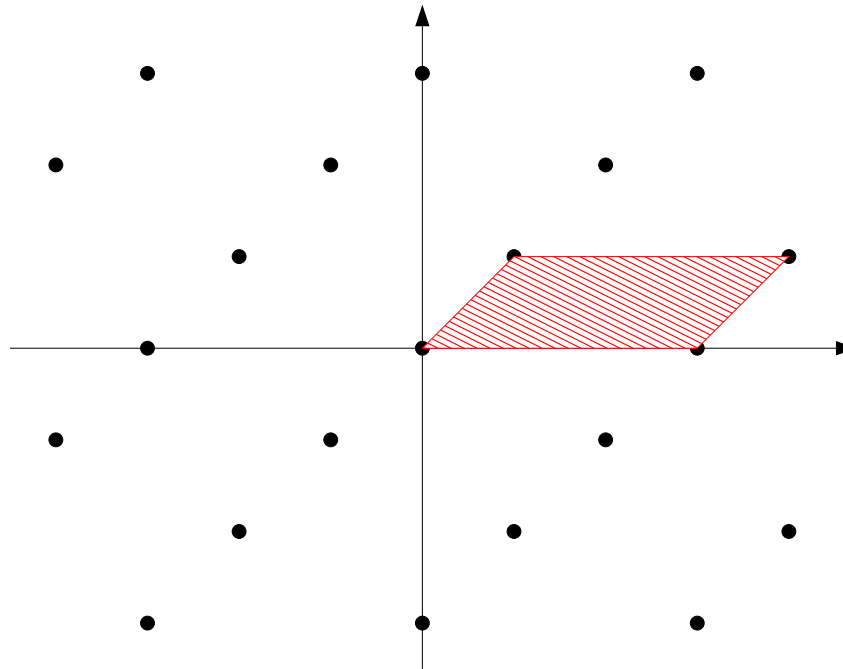
Set $X = \Gamma \backslash G = \{\Gamma g : g \in G\}$ — our **homogeneous space**.

Let μ be a left Haar measure on G ; then μ induces a G -invariant measure on $\Gamma \backslash G$ which we *also* call “ μ ”. From now on we assume that μ is normalized so that $\mu(\Gamma \backslash G) = 1$.

– see Problem 2

Example: $G = \mathbb{R}^d$, $\Gamma = L$, a lattice in \mathbb{R}^d .

That is: $L = \{c_1\vec{v}_1 + \cdots + c_d\vec{v}_d : c_1, \dots, c_d \in \mathbb{Z}\}$ for some $\vec{v}_1, \dots, \vec{v}_d \in \mathbb{R}^d$ which form a basis of \mathbb{R}^d .



Then $X = \Gamma \backslash G = L \backslash \mathbb{R}^d = \mathbb{R}^d / L$, a *torus*.

μ = normalized Lebesgue measure.

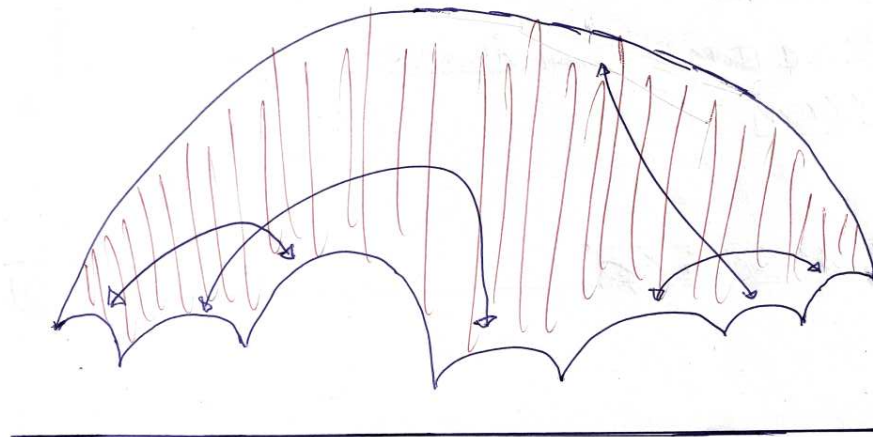
Example: $G = \mathrm{SL}_2(\mathbb{R})$ and Γ a lattice in G with $-I \in \Gamma$, and without elliptic elements.

Recall that $\mathrm{SL}_2(\mathbb{R})$ acts by isometries on the hyperbolic upper half space:

$$\mathbf{H} = \{z = x + iy : x, y \in \mathbb{R}, y > 0\}, \quad \text{with metric } ds = \frac{\sqrt{dx^2 + dy^2}}{y}.$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} (z) = \frac{az + b}{cz + d}.$$

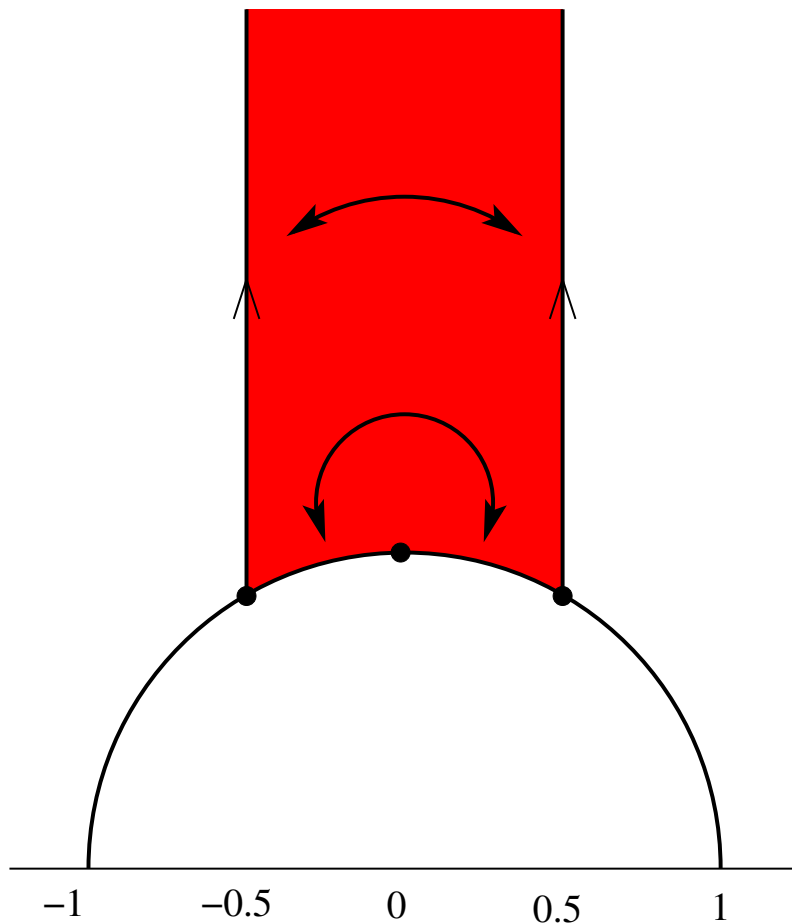
Now $\Gamma \backslash \mathbf{H}$ is a hyperbolic surface of finite area, and $X = \Gamma \backslash G = T^1(\Gamma \backslash \mathbf{H})$, viz., $\Gamma \backslash G$ can be identified with the unit tangent bundle of $\Gamma \backslash \mathbf{H}$.



– see Problem 1

For $G = \mathrm{SL}_2(\mathbb{R})$, $\Gamma = \mathrm{SL}_2(\mathbb{Z})$

$X = \Gamma \backslash G = T^1(\Gamma \backslash \mathbf{H})$, where $\Gamma \backslash \mathbf{H}$ looks as follows:



Example: $G = \mathrm{SL}_d(\mathbb{R})$ and $\Gamma = \mathrm{SL}_d(\mathbb{Z})$ ($d \geq 2$). Then

$X = \Gamma \backslash G = \mathrm{SL}_d(\mathbb{Z}) \backslash \mathrm{SL}_d(\mathbb{R}) =$ **[the space of lattices in \mathbb{R}^d of covolume 1].**

Identification map: $\Gamma g \mapsto \mathbb{Z}^d g = \{\vec{x}g : \vec{x} \in \mathbb{Z}^d\}$ ($g \in G$).

X is **noncompact**.

Mahler's criterion: A sequence $\Gamma g_1, \Gamma g_2, \dots$ in $\Gamma \backslash G$ *diverges*

($\stackrel{\text{def}}{\iff}$ leaves every compact subset of $\Gamma \backslash G$)

if and only if

$$m(\Gamma g_j) := \min\{\|\vec{x}g_j\| : \vec{x} \in \mathbb{Z}^d \setminus \{\vec{0}\}\} \rightarrow 0 \quad \text{as } j \rightarrow \infty.$$

Next: **DYNAMICS** on the homogeneous space $X = \Gamma \backslash G$

Let $(h_t)_{t \in \mathbb{R}}$ be a *1-parameter subgroup* of G .

(That is, the map $t \mapsto h_t$ is a Lie group homomorphism. Recall that in this situation there exists a unique element $X \in \mathfrak{g}$ such that $h_t = \exp(tX)$, $\forall t \in \mathbb{R}$.)

Objective: Understand properties of the “**homogeneous flow**”

$$\Phi_t(\Gamma g) := \Gamma g h_t \quad \text{on } X = \Gamma \backslash G.$$

(Note that this flow preserves μ .)

FLOWS (a basic notion in dynamical systems)

A **flow** on a set X is a map $\Phi : \mathbb{R} \times X \rightarrow X$ such that

$$\forall x \in X, t, s \in \mathbb{R} : \quad \Phi(0, x) = x \quad \text{and} \quad \Phi(s, \Phi(t, x)) = \Phi(s + t, x).$$

We will write $\Phi_t(x)$ in place of $\Phi(t, x)$. Then:

$$\forall x \in X, t, s \in \mathbb{R} : \quad \Phi_0(x) = x \quad \text{and} \quad \Phi_s(\Phi_t(x)) = \Phi_{s+t}(x).$$

Note: For each $t \in \mathbb{R}$, Φ_t is a bijection $X \xrightarrow{\sim} X$.

Compare with a (bijective) **map** $T : X \rightarrow X$; then study $T^{\circ n} : X \rightarrow X$ for $n \in \mathbb{Z}$ — for a **flow** we take instead “ $n \in \mathbb{R}$ ”.

Usually X has extra structure which Φ preserves.

Ex: X a topological space, and $\Phi : \mathbb{R} \times X \rightarrow X$ *continuous*.

Ex: X a C^∞ manifold, and $\Phi : \mathbb{R} \times X \rightarrow X$ is C^∞ .

We say that the flow Φ **preserves a measure** $\mu \in P(X)$ if $\Phi_{t*}(\mu) = \mu$ for all $t \in \mathbb{R}$ (that is, $\mu(\Phi_{-t}(A)) = \mu(A)$ for every measurable $A \subset X$).

In this situation, μ **is ergodic** if, for every measurable subset $A \subset X$ satisfying $\Phi_t(A) = A$, $\forall t \in \mathbb{R}$, one has $\mu(A) = 0$ or 1 .

Birkhoff's **Pointwise Ergodic Theorem** for flows: Let (X, \mathcal{B}, μ) be a probability space; and let $\Phi : \mathbb{R} \times X \rightarrow X$ be a measurable flow preserving μ . Let $f : X \rightarrow \mathbb{C}$ be measurable and $\int_X |f| d\mu < \infty$. Set

$$A_T^f(x) := \frac{1}{T} \int_0^T f(\Phi_t(x)) dt \quad (T > 0).$$

Then the function A_T^f converges μ -almost everywhere, and also in L^1 -norm, to a function $F : X \rightarrow \mathbb{C}$ with $F \circ \Phi_t \equiv F$ ($\forall t \in \mathbb{R}$).

DYNAMICS on the homogeneous space $X = \Gamma \backslash G$

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Objective: Understand properties of the “homogeneous flow”

$$\Phi_t(\Gamma g) := \Gamma g h_t \quad \text{on } X = \Gamma \backslash G.$$

(Note that this flow preserves μ .)

Examples: Let $G = \mathrm{SL}_2(\mathbb{R})$.

Let $a_t \equiv \begin{pmatrix} e^{t/2} & 0 \\ 0 & e^{-t/2} \end{pmatrix}$: $\Phi_t(\Gamma g) := \Gamma g a_t$ is the **geodesic flow** on $T^1(\Gamma \backslash \mathbf{H})$.

Let $u_t \equiv \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}$: $\Phi_t(\Gamma g) := \Gamma g u_t$ is the **horocycle flow** on $T^1(\Gamma \backslash \mathbf{H})$.

– see Problem 1

For general $\Gamma \backslash G$ and (h_t) , the behavior of the flow $\Phi_t(\Gamma g) = \Gamma g h_t$ can differ hugely, depending on (h_t) (and on G)! Two important, very different, cases:

$$\boxed{(h_t) \text{ unipotent}} \stackrel{\text{def}}{\iff} \left[\text{Ad}_{h_t} \text{ is unipotent } (\forall t \in \mathbb{R}) \right].$$

Examples: The horocycle flow: $G = \text{SL}_2(\mathbb{R})$ and $u_t \equiv \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}$.

More generally, $G = \text{SL}_d(\mathbb{R})$ and any $u_t \equiv \begin{pmatrix} 1 & * & * & \cdots & * \\ 0 & 1 & * & \cdots & * \\ 0 & 0 & 1 & & * \\ \vdots & \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & 0 & 1 \end{pmatrix}$.

Also: $G = \mathbb{R}^d$ ($\Rightarrow X$ a torus, and all homogeneous flows are *linear*).

$$\boxed{(h_t) \text{ (\mathbb{R}-)diagonal}} \stackrel{\text{def}}{\iff} \left[\text{Ad}_{h_t} \text{ is diagonalizable over } \mathbb{R} (\forall t \in \mathbb{R}), \text{ and } G \text{ is a simple Lie group with finite center.} \right]$$

((Or more generally, G *semisimple* + extra conditions.))

Examples: The geodesic flow: $G = \text{SL}_2(\mathbb{R})$ and $a_t \equiv \begin{pmatrix} e^{t/2} & 0 \\ 0 & e^{-t/2} \end{pmatrix}$.

More generally, $G = \text{SL}_d(\mathbb{R})$ and $a_t \equiv \begin{pmatrix} e^{c_1 t} & 0 & \dots & 0 \\ 0 & e^{c_2 t} & & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \dots & e^{c_d t} \end{pmatrix}$.

Summary of properties

Diagonal flows are “**chaotic**”:

— they are *Bernoulli*,
have *positive entropy*,
non-zero Lyapunov exponents (\Rightarrow are *partially hyperbolic*),
and are *exponentially mixing*.

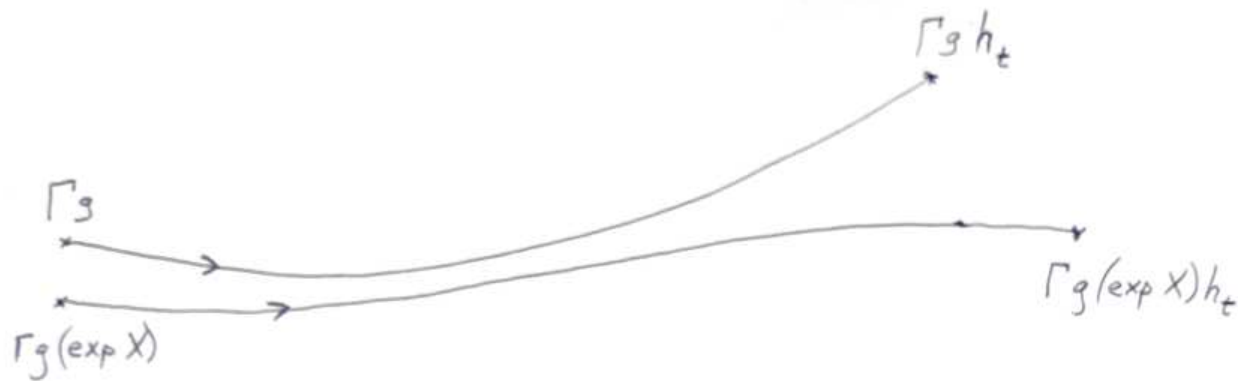
Unipotent behave in a much more controlled way:

— they have *entropy zero* (\Rightarrow they are “**deterministic**”),
they have *all Lyapunov exponents* = 0,
they are *at most polynomially mixing* (see Problem 4(c)),
and they exhibit *measure rigidity* (Ratner’s Theorem).

Immediate consequences of the definitions (unipotent/diagonal)

Note, for any $g \in G$ and $X \in \mathfrak{g}$:

$$\Gamma g(\exp X)h_t = \Gamma gh_t \exp\left(\text{Ad}_{h_t}^{-1}(X)\right).$$



Therefore,

$$(h_t) \begin{cases} \text{unipotent} \\ \text{diagonal} \end{cases} \Rightarrow \begin{cases} \text{polynomial} \\ \text{exponential} \end{cases} \text{ divergence of trajectories.}$$

– see Problem 4

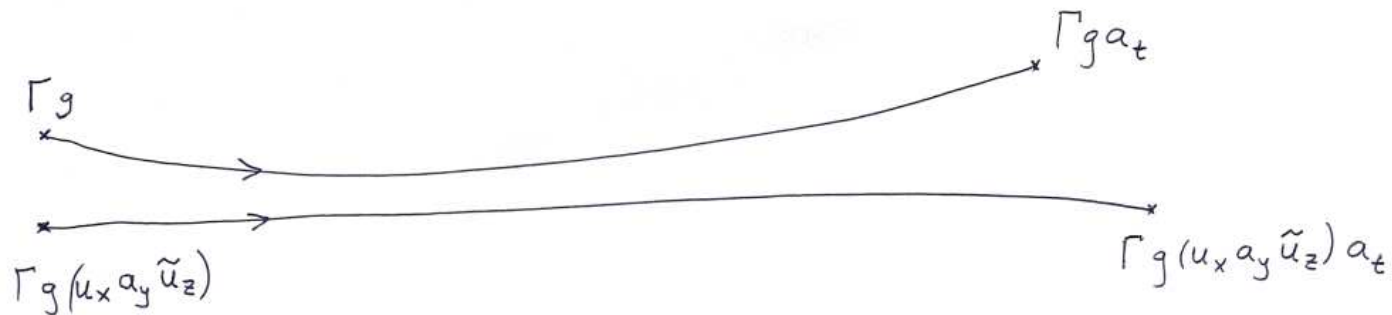
More concretely, and explicitly, for $G = \mathbf{SL}_2(\mathbb{R})$

Write $a_y = \begin{pmatrix} e^{y/2} & 0 \\ 0 & e^{-y/2} \end{pmatrix}$, $u_x = \begin{pmatrix} 1 & x \\ 0 & 1 \end{pmatrix}$, $\tilde{u}_z = \begin{pmatrix} 1 & 0 \\ z & 1 \end{pmatrix}$.

Then $\langle x, y, z \rangle \mapsto u_x a_y \tilde{u}_z$, $\mathbb{R}^3 \rightarrow G$, is a C^∞ parametrization of $G_+ := \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in G : d > 0 \right\}$. (Note also $\langle 0, 0, 0 \rangle \mapsto \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$.)

Key relations: $u_x a_t = a_t u_{xe^{-t}}$ and $\tilde{u}_z a_t = a_t u_{zet}$

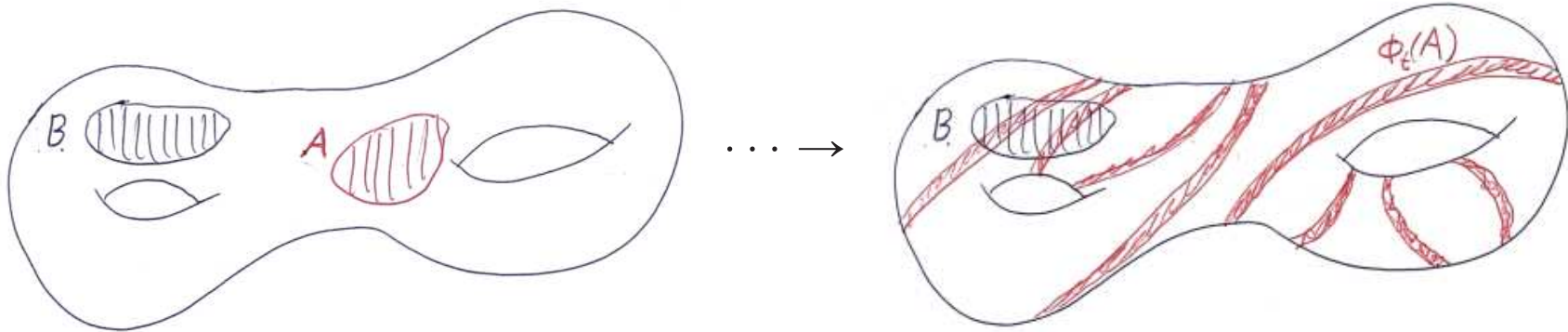
It follows that $\Gamma g \left(u_x a_y \tilde{u}_z \right) a_t \equiv \Gamma g a_t \left(u_{xe^{-t}} a_y \tilde{u}_{zet} \right)$.



Mixing (a basic notion in dynamical systems)

Definition: A measure-preserving flow (Φ_t) on a probability space (X, μ) is said to be **(strongly) mixing** if

(i) for any $A, B \subset X$, $\lim_{t \rightarrow \infty} \mu(\Phi_t(A) \cap B) = \mu(A)\mu(B)$,



or equivalently

(ii) $\forall f_1, f_2 \in L^2(X, \mu): \lim_{t \rightarrow \infty} \langle f_1 \circ \Phi_t^{-1}, f_2 \rangle = \mu(f_1)\mu(f_2)$.

(Proof of (i) \Leftrightarrow (ii): “Simple functions are dense in L^2 ”.)

Note: **mixing** \Rightarrow **ergodic**

Diagonal flows are exponentially mixing

Theorem (work by *many* people):

Let G be a simple Lie group with finite center, and let Γ be a lattice in G .
(Example: $G = \mathrm{SL}_d(\mathbb{R})$, Γ any lattice in G .)

Set $X = \Gamma \backslash G$, and let (a_t) be a non-trivial, **\mathbb{R} -diagonal** one-parameter subgroup of G . Then $\exists \ell \in \mathbb{Z}^+$, $C > 0$, $\eta > 0$ such that

$\forall f_1, f_2 \in C_c^\infty(X)$, $t \geq 0$:

$$\left| \int_X f_1(x a_{-t}) f_2(x) d\mu(x) - \mu(f_1)\mu(f_2) \right| \leq C \cdot S_{2,\ell}(f_1) S_{2,\ell}(f_2) \cdot e^{-\eta t}.$$

(On the other hand, a unipotent flow can be *at most polynomially mixing*
— see Problem 4(c).)

Application: Equidistribution of expanding horocycles in $SL_2(\mathbb{R})$ (“Margulis’ thickening technique”)

Theorem: Let $G = SL_2(\mathbb{R})$, let Γ be a lattice in G , and set $X = \Gamma \backslash G$. Then for any $p_0 \in X$ and $f \in C_c(X)$:

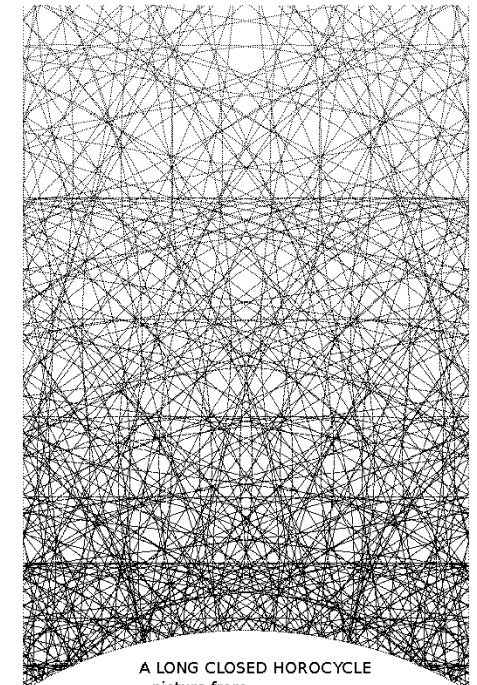
$$\int_0^1 f(p_0 u_s a_t) ds \rightarrow \mu(f) \quad \text{as } t \rightarrow -\infty.$$

Remarks:

- For $p_0 = \Gamma \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ and Γ with $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \in \Gamma$:

Equidistribution of long closed horocycles,
very classical (Selberg, Zagier, Sarnak, Hejhal, ...)

- the theorem is proved using the fact that (a_t) is mixing. Using **exponential** mixing, one also obtains an **error term**.



A LONG CLOSED HOROCYCLE
- picture from
www-users.math.umn.edu/~hejhal/

Outline of proof: (See Problem 5 for details.)

Naively, we want to apply the fact that (a_t) is **mixing**, with

$$f_2 \equiv f \quad \text{and} \quad f_1 = \left[\text{1-dim Lebesgue measure along } \{p_0 u_s : 0 \leq s \leq 1\} \right].$$

However, that f_1 is *not permitted!*

To fix up, instead take f_1 to be the *characteristic function of*

$$H_{p_0, \varepsilon} := \left[\varepsilon\text{-neighbourhood of } \{p_0 u_s : 0 \leq s \leq 1\} \right].$$

Using the fact that (a_t) is **mixing**, we get:

$$\lim_{t \rightarrow -\infty} \int_X f_1(x a_{-t}) f_2(x) d\mu(x) = \mu(f_1) \mu(f_2)$$

$$\Rightarrow \lim_{t \rightarrow -\infty} \frac{1}{\mu(f_1)} \int_X f_1(x) f_2(x a_t) d\mu(x) = \mu(f_2)$$

$$\Rightarrow \lim_{t \rightarrow -\infty} \frac{1}{\mu(H_{p_0, \varepsilon})} \int_{H_{p_0, \varepsilon}} f_2(x a_t) d\mu(x) = \mu(f_2).$$

In the last integral, use the fact that $H_{p_0, \varepsilon} a_t$ is contained in an ε -neighbourhood of

$$\{p_0 u_s a_t : 0 \leq s \leq 1\},$$

because of

$$p_0 u_s (a_y \tilde{u}_z) a_t = p_0 u_s a_t (a_y \tilde{u}_{ze^{-t}}).$$

(Recall $t \rightarrow -\infty$.)

Therefore,

$$\frac{1}{\mu(H_{p_0, \varepsilon})} \int_{H_{p_0, \varepsilon}} f_2(x a_t) d\mu(x) \approx \int_0^1 f_2(p_0 u_s a_t) ds,$$

and we are done. □

Measure rigidity for unipotent flows (Ratner)

Theorem (Ratner, 1991): Let G be a Lie group and Γ a lattice in G , and let $\Phi_t(\Gamma g) = \Gamma g u_t$ be a **unipotent** flow on $X = \Gamma \backslash G$. Then every

$$\Phi_t\text{-invariant ergodic } \nu \in P(X)$$

is **“homogeneous”** (\Leftrightarrow **“algebraic”**),

meaning that there exist $x \in X$ and a closed connected subgroup $S \subset G$ such that $\{u_t\} \subset S$, $xS = \overline{\{\Phi_t(x) : t \in \mathbb{R}\}}$, $\nu(xS) = 1$ and ν is S -invariant.

In the above situation, it follows that ν is the *unique* S -invariant probability measure on xS ; and also that $\Phi_{\mathbb{R}}(x)$ is *equidistributed* in xS .

Also, xS is a *closed regular submanifold* of X . Explicitly, take $g \in G$ such that $x = \Gamma g$, and set $\tilde{S} = gSg^{-1}$, $\tilde{\Gamma} = \Gamma \cap \tilde{S}$ and $\tilde{X} = \tilde{\Gamma} \backslash \tilde{S}$. Then $\tilde{\Gamma}$ is a *lattice* in \tilde{S} , and the map

$$J : \tilde{X} \rightarrow X, \quad J(\tilde{\Gamma}\tilde{s}) := \Gamma\tilde{s}g \quad (\tilde{s} \in \tilde{S})$$

is a C^∞ diffeomorphism of \tilde{X} onto xS , mapping the \tilde{S} -invariant measure of \tilde{X} onto ν .